



ARCHON AUTONOMOUS D R O N E S

Fully autonomous **drones**
providing inspection, monitoring, surveillance
services to the industry

Daide Ghezzi
Cofounder

Drones are not robot yet. They need a **pilot**.

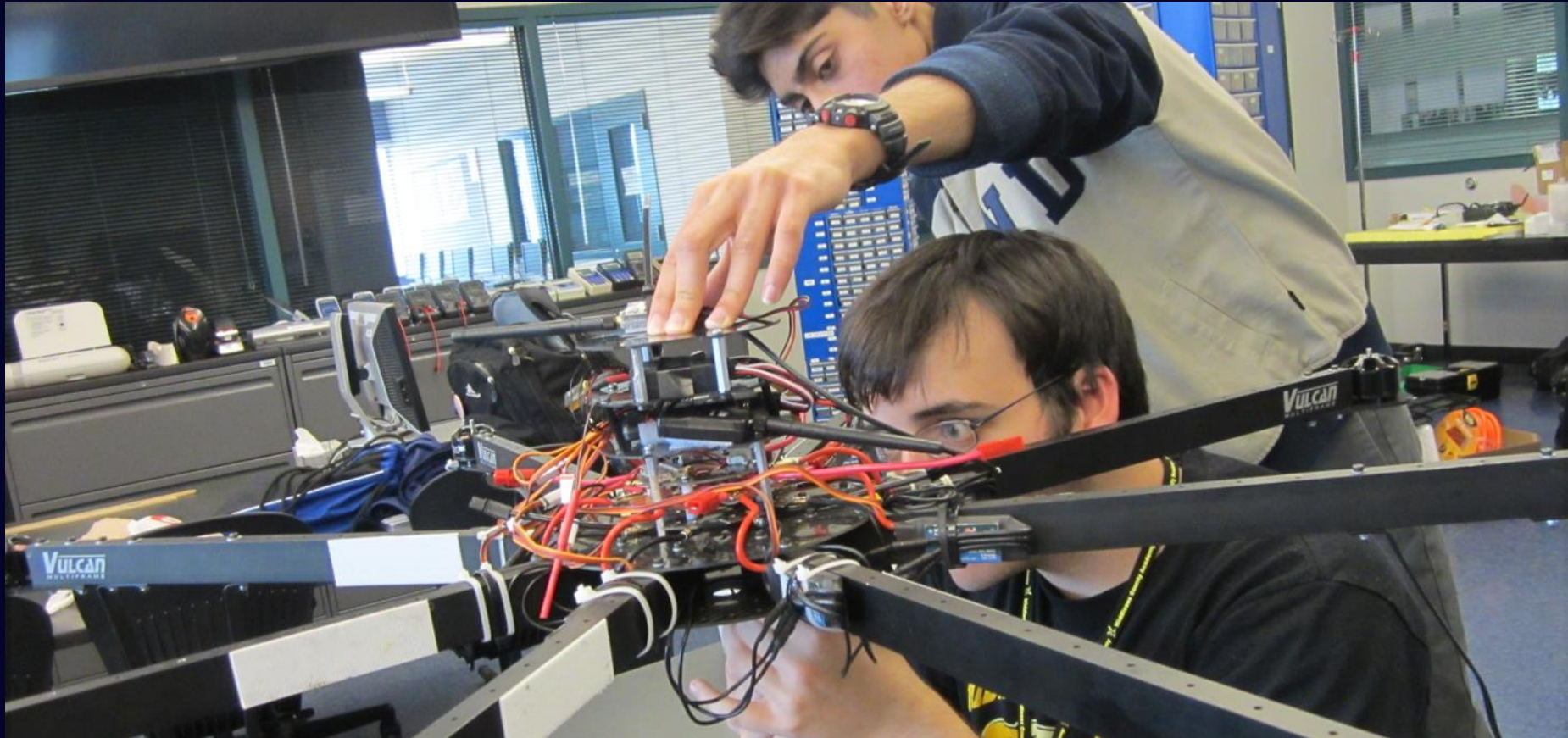


Or they need careful programming

```
usage: module load \n
STABILIZE> module load
DroneAPI loaded
Loaded module droneapi
STABILIZE> api list
API Threads:
STABILIZE> api start s
Arming and taking off
STABILIZE> Got MAVLink
timeout setting ARMING
Waiting for arming...
Waiting for arming...
Waiting for arming...
Waiting for arming...
APM: ARMING MOTORS
APM: GROUND START
Waiting for arming...
APM: Initialising APM.
Got MAVLink msg: COMM
Waiting for arming...
ARMED
Taking off!
```



And their battery needs to be **recharged** often



What is a truly **gamechanging** solution?

Fully autonomous, **robotized** drones, intelligently auto-recharging

Drones



**Reliable
products
available in
the market
+
wheels**

Wheels for autonomous, non-precise landing



Fully autonomous, **robotized** drones, intelligently auto-recharging

Drones

+

Landing /
recharging
stations



Reliable
products
available in
the market
+
wheels



Autonomous,
non-precise
landing
even under
adverse weather
conditions

Recharging station: docking 4 to 8 drones



Fully autonomous, **robotized** drones, intelligently auto-recharging

Drones

+

Landing /
recharging
stations

+

Artificial Intelligence



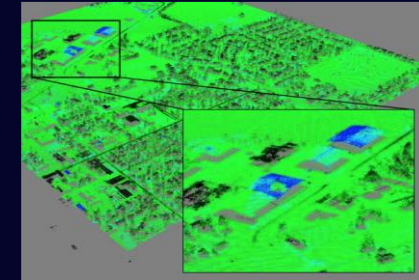
Reliable
products
available in
the market
+
wheels



Autonomous,
non-precise
landing
even under
adverse weather
conditions



Optimized
Flight
Randomized
patrols
Automatic
drone
switching

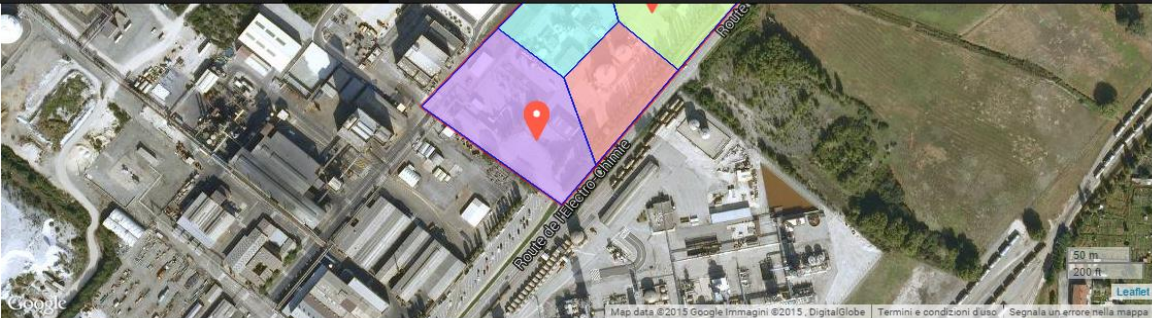


Lidar 3D Map
Integration
Real-time video
Response to
alarm

Mission planner for non-experts, non-pilots

ec2-52-10-190-255.us-west-2.compute.amazonaws.com/#maps/5/services/4/planning

Archon Dashboard



Max Permanency 0
Max Time 0 min

Mission Definition

☒ Alarm Sector #0 ☒ Alarm Sector #2 ☒ Alarm Sector #3 ☒ Alarm Sector #1

☒ Day patrol ☒ Night patrol

Plan name Add custom plan

Mission Details

Each alarm should have a different priority

Alarm Sector #0

Alarm priority:

Total time		6		min	
#	Sector priority		Sector time		
0	100	%	1	min	
1	0	%	1	min	

Alarm Sector #1

Alarm priority:

Total time		4		min	
#	Sector priority		Sector time		
0	20	%	1	min	
1	80	%	1	min	

Alarm Sector #2

Alarm priority:

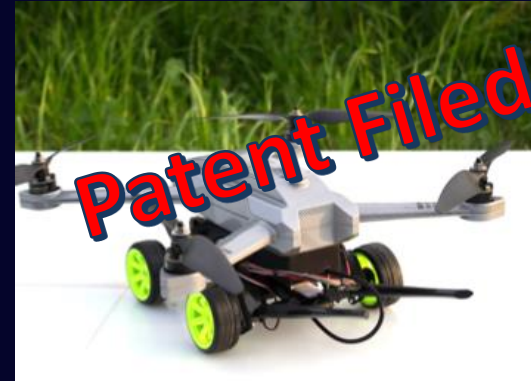
Total time		3		min	
#	Sector priority		Sector time		
0	10	%	1	min	
1	50	%	1	min	

Intellectual Property

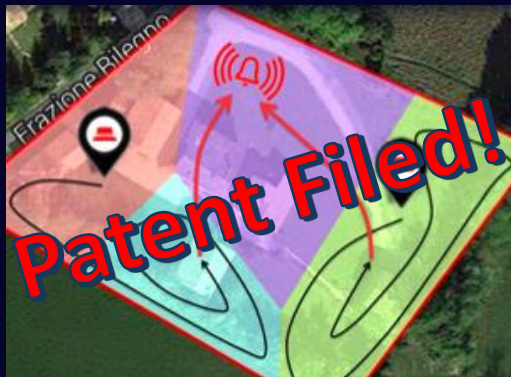
Control of fleet of Drones



Auto Land & Recharge



Flight intelligence

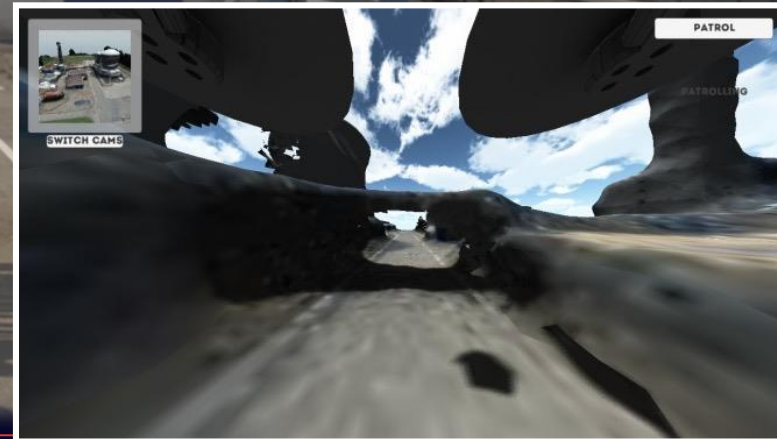


+

Data analysis & report

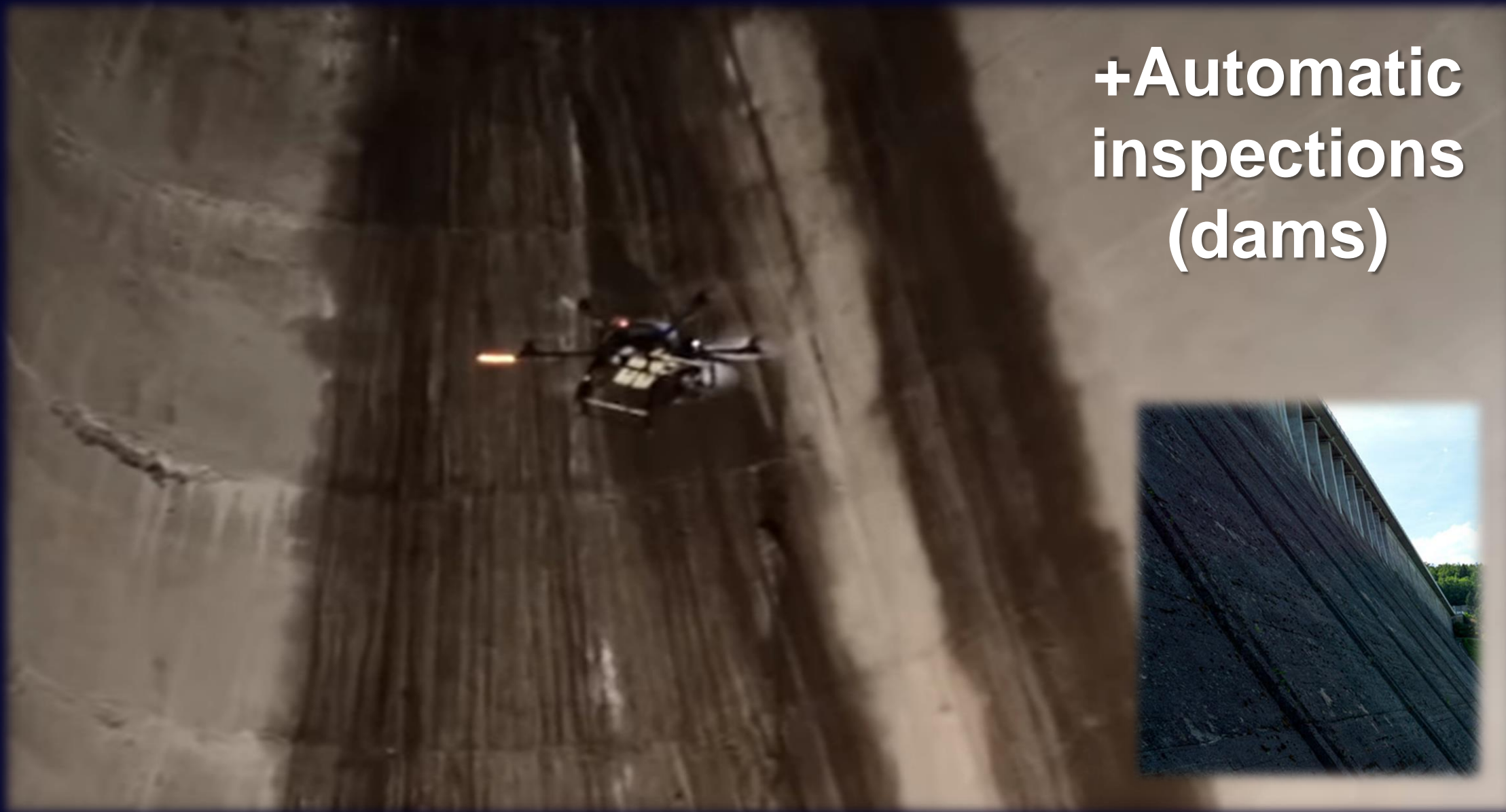


Automatic inspections (chemical)

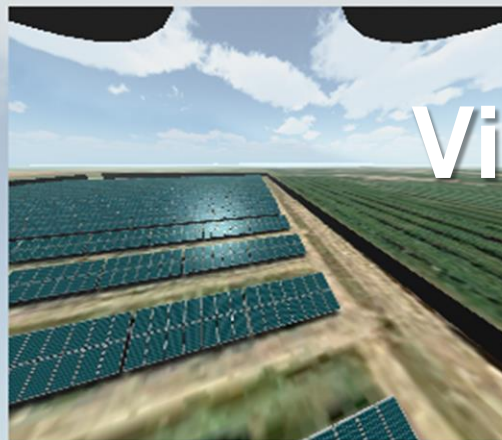


**+Automatic
inspections
(energy)**



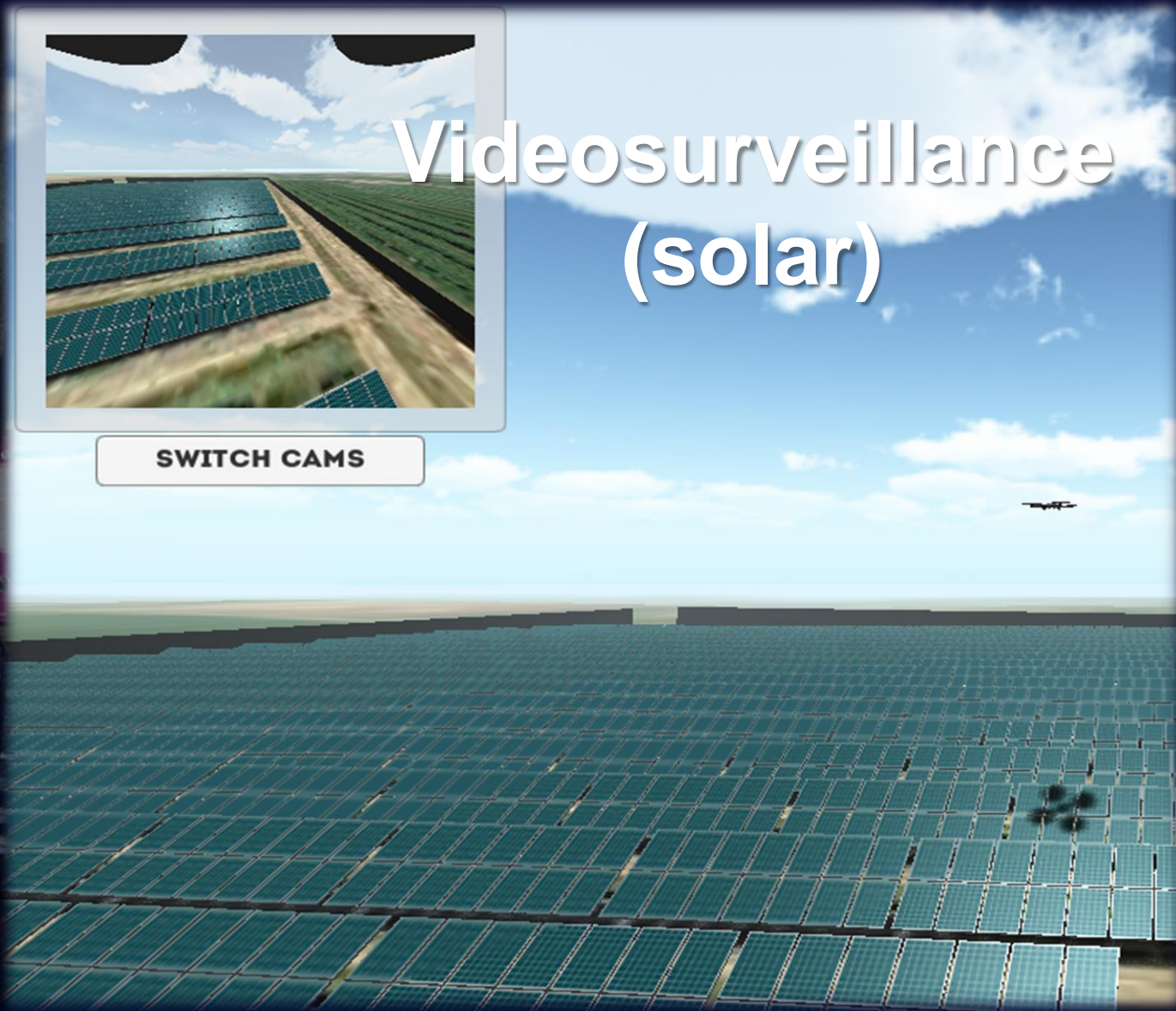


**+Automatic
inspections
(dams)**

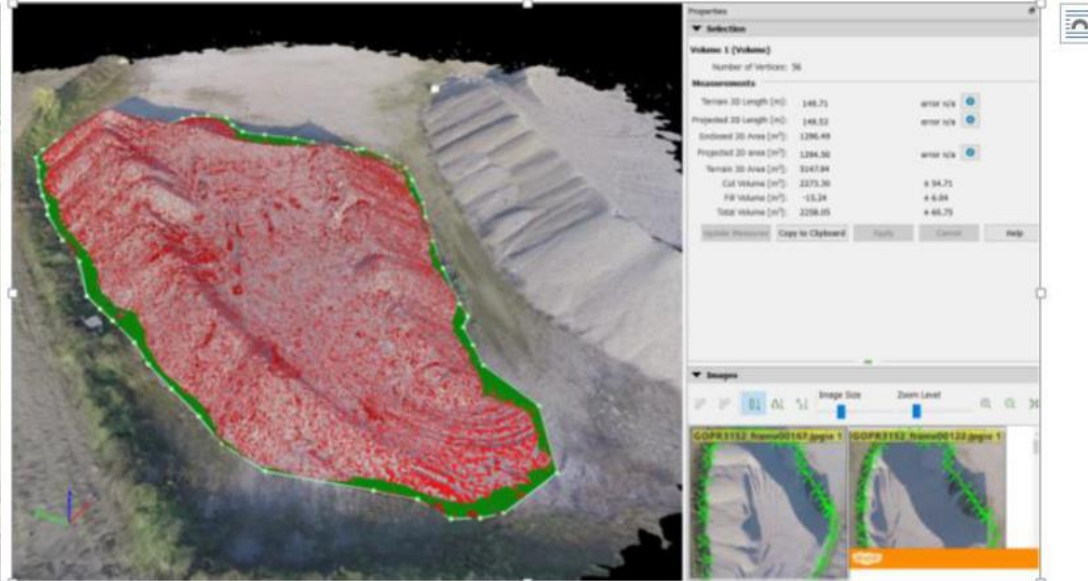
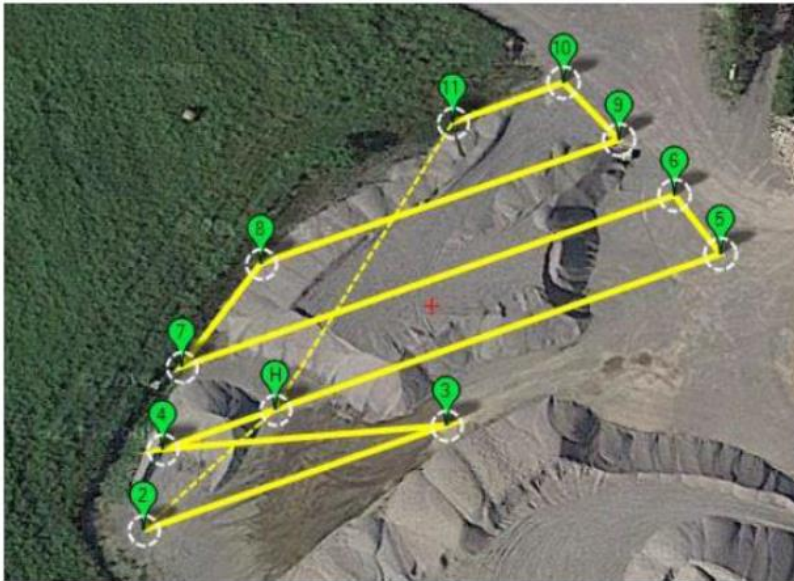


SWITCH CAMS

Videosurveillance (solar)

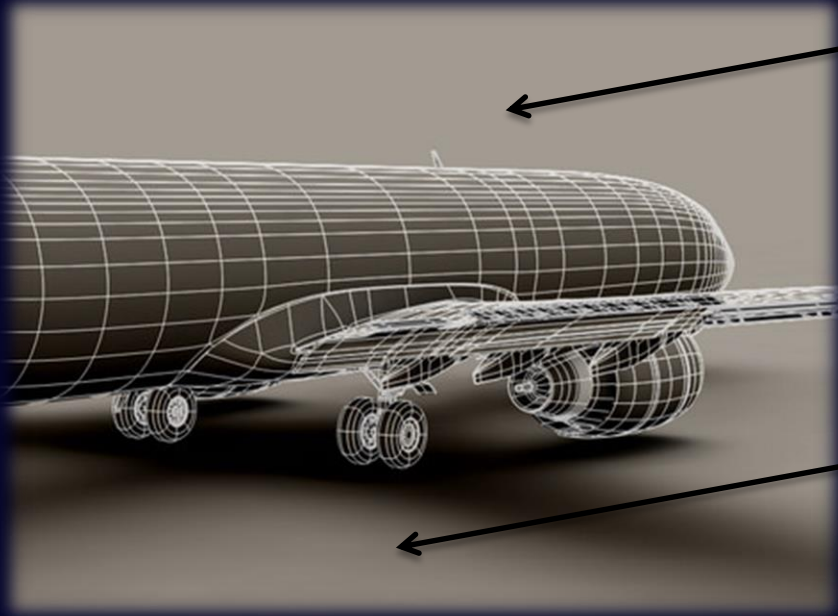


+Data Analysis
mapping
(construction)



Aircraft inspections

Pre-existing 3D model



Flying Drone



Mobile Recharge Station and Robot

- Move the system close to the aircraft
- Press a button, the AI understand where it is
- Get a quality report after 20-30 min



Business Model

Pre-contract engagement

- Feasibility study
- Virtual simulation
- Simple manned operations
- Collaboration with service providers



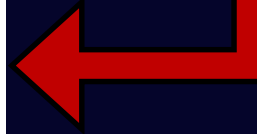
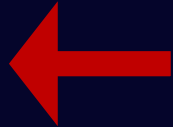
Test-bed experimentation

- Hardware installation and integration
- Different tests and models of interaction with personnel
- Set-up control room
- Set up reporting system



Deployment at scale

- Contract for 10+ installations for 3+ years
- End-to-end control of the solution, incl. maintenance
- Non-exclusivity deal (possible co-investment)





Davide Venturelli

Cofounder, Acting CEO
PhD Physics & Simulations
Quantum AI international expert
20+ publications, 200+ citations
NASA Scientist & Manager



Roberto Navoni

Cofounder, CTO, Hardware
PM
Lead company with 10+ engineers
and with **20+ years experience in
robotics and mechatronics**
International reputation in drone
tech.



Giovanni Landi

CXO, 3D Programming, UX
Advanced computer Graphics
and Animations
Researcher Virtual Reality
International VR awards



Davide Ghezzi

Cofounder, BuzDev.
MBA Columbia,
JP Morgan London,
Mediobanca, Solar PE fund.
2 start-up exits



Daniele Stanzani

Software PM
Senior Software Engineer,
10 years experience
Reliability Engineer **Ferrari** GP
Computer Security Expert



Ciro Farinelli

R&D Program Manager
Aerospace Engineer (Polytech MI)
Previously **Project Manager Airbus**
Jr. Researcher at KAIST (Korea)
Entrepreneurial startup experience

Fundraising plans

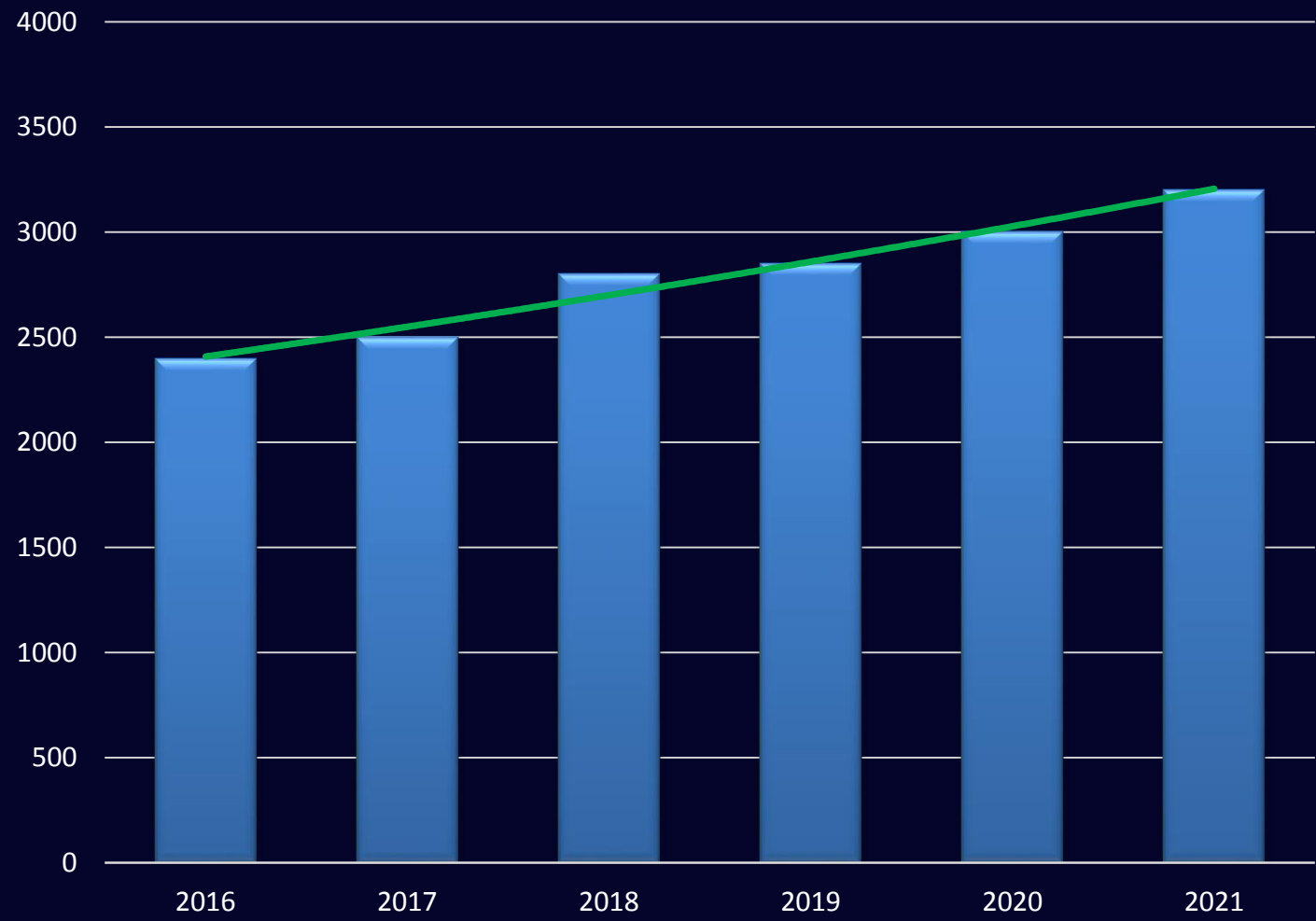
€ 500k bridge with “strategic angels” - now
€ 3.0m Round A - by end 2016

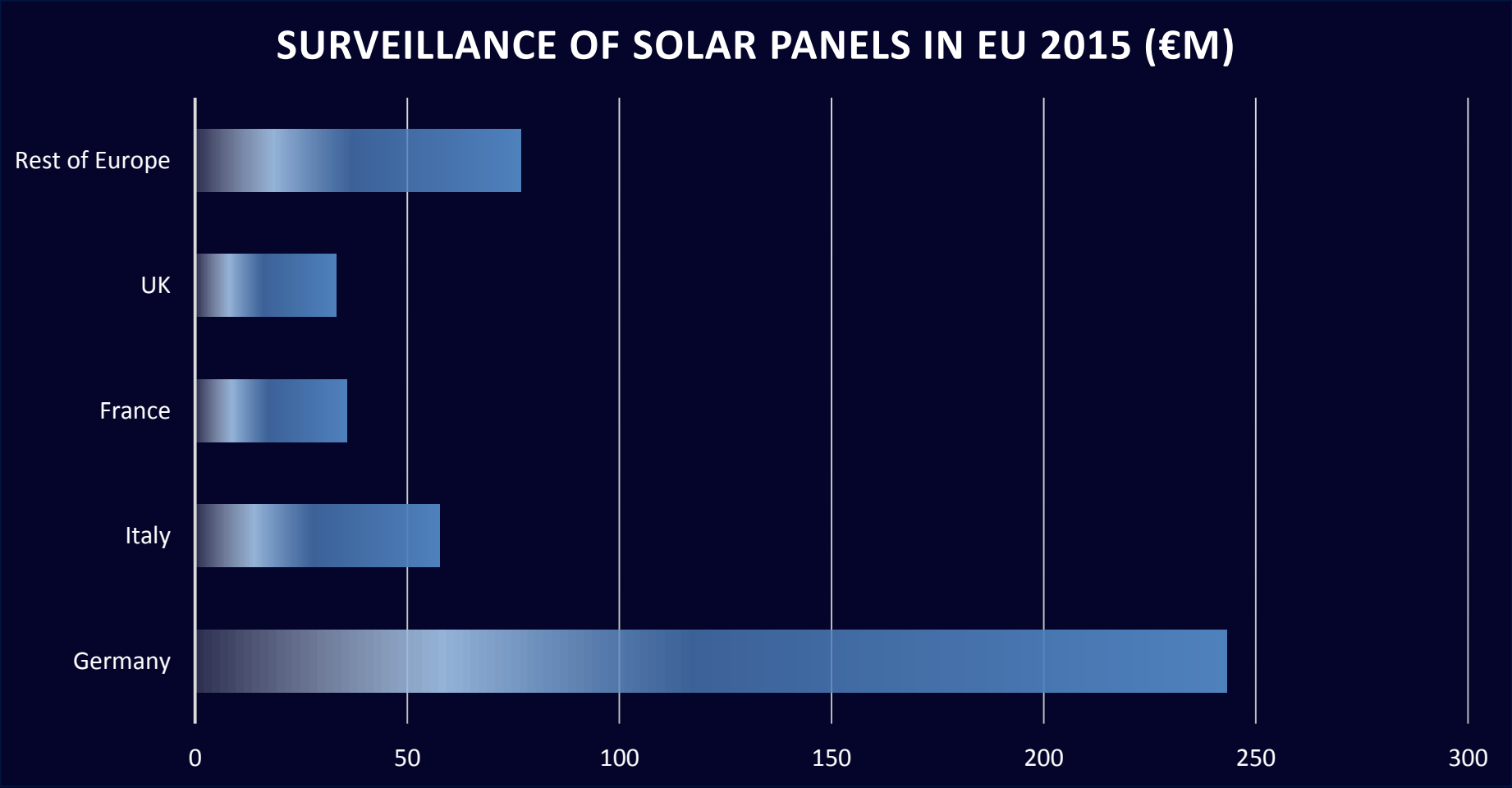
- Plan of attack of a large market **waiting to be disrupted** (security/inspection services \$200B+)
- **Near-term plan:** recruiting, patenting, tests, feasibility studies, experimentations. Target: **First deployment of the system on a customer site by Q4 2016**
- Layered flexible business model, **several revenue streams**, ready for regulation changes.
- **Valuable IP:** robust drone landing with wheels, multi-uav strategy, station, virtual control room.

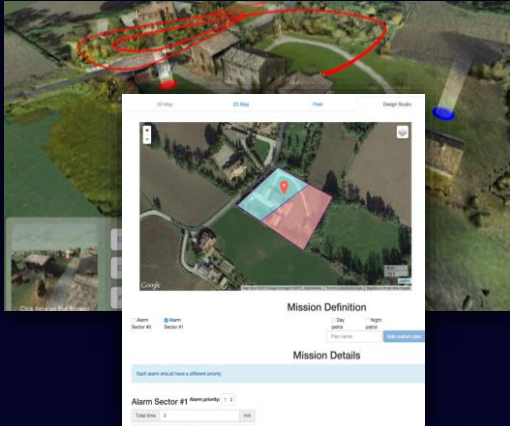
Thank you

Davide Ghezzi
dg@archon.ai

EU SURVEILLANCE MARKET 2015 (€M)







- A.I. to plan fault tolerant missions
- GUI to design the service
- 3D Simulations of the service
- Landing and recharging modules
- Filed 2 provisional patents

2016

- Mostly targeting photovoltaic and inspection of industrial assets
- Basic autonomous drone system with 2 drones and 2 stations for false alarm verification.

Significant traction with:



2017

- Test different case studies with large value customers
- Increase the power of technology (interactions, artificial vision, Virtual Reality)



- Unique technology for auto-management of coordinated drones, using **state-of-art (drones API, 3D virtual reality) and beyond (NASA-like AI)**.
- Plan of attack of a large market **waiting to be disrupted** (security/inspection services \$200B+)
- Secured funding from grants for tests and initiated more grants. No equity given, collected money will go to **new hires and better product**.
- Precise **near-term plan**: recruiting, patenting, tests, feasibility studies, experimentations. Target: **First deployment of the system on a customer site Q1-Q2 2016**
- Layered flexible business model, **several revenue streams**, ready for regulation changes.
- **Valuable IP**: robust drone landing with wheels, multi-uav strategy, station, virtual control room.

Projections: round A investment €3M

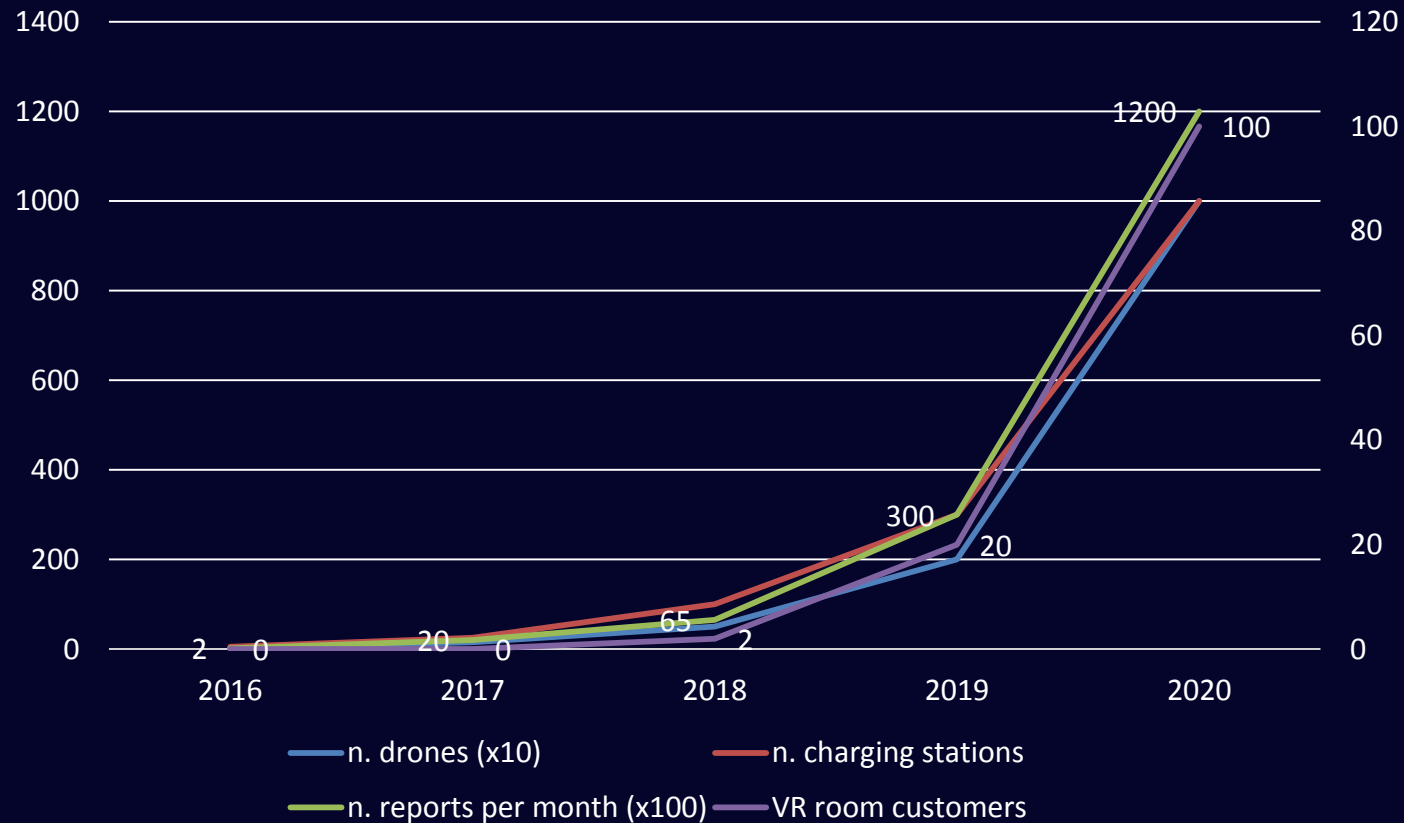
- Assumption of getting 1.5M€ grants for R&D, with LaserNav
- Sought valuation: 20-30M€ depending on the agreement with LaserNav

	Total	2016 (Q3-Q4)	2017	2018 (Q1-Q2)
Grants/Revenues PIRD Project	€1,500,000	€250,000	€750,000	€500,000
Acceleration PIRD Project	€300,000	€100,000	€200,000	€0
Indirect Costs	€540,000	€10,000	€30,000	€500,000
Additional workforce	€250,000	€50,000	€100,000	€100,000
Management	€420,000	€90,000	€150,000	€180,000
San Francisco (USA operations)	€400,000	€100,000	€100,000	€200,000
Legal / IP / Internationalization	€160,000	€40,000	€50,000	€70,000
Travel costs	€70,000	€10,000	€20,000	€40,000
Hardware Production Investments	€400,000	€50,000	€200,000	€150,000
Complementary QA and testing	€110,000	€0	€35,000	€75,000
Demos, experim. and marketing	€350,000	0	€50,000	€300,000
	€4,500,000	€700,000	€1,685,000	€2,115,000

KPIs

- Number of flying drones and charging stations
- Quantity of Data going through Archon Sentinel Cloud
- How many customers the Virtual Reality Room is serving

KPIs forecast



Go To Market Plan

